

嘉模阿波羅 與 香港走向智能製造現代化

Karmo Apollo + Robotics Automation + Government





Company Introduction



Company Background

- Established in Year 1972
- Previous developing automation in plastic industry is the core business
- Currently focused in developing 3 Businesses:





Robotics Solution

 \triangleright



Industrial Machinery

Solution

 \triangleright



	\triangleright	Product Development &	Ş
--	------------------	-----------------------	---

Product Adaptation



Recent Projects – Printing Automation (2014 - 2017)

- ▷ Project Aim :
 - D To increase the quality of printing, feeding & transportation
 - D To increase the stability of product quality and quantity
 - ▷ To integrate into ERP (Industrial 4.0)









Recent Projects – The Billie Upcycling (2018)

▷ Project Aim :

- D To Reindustrialize Hong Kong
- To Promote Recycling









Smart Warehouse



What is a Smart Warehouse System ?



Automated Pick & Place Cargo System

Inventory database with management system Automatic Ground Vehicle for heavy loading cargo distribution



Advantages of Smart Warehouse System



Increase in productivity by transferring repetitive procedure to automated machine



Reduce risk of injury from different hazards in loading/unloading heavy cargo



Increase in efficiency by utilizing machine use



Components of Smart Warehouse System









Control Unit

Main coordination & control unit, could be interact by GUI

Database Server

Server that stored inventory data and transaction logging

0	

Cargo

Stored object with unique tags to digitize information

Pick & Place System

Mechanical system for transferring cargo

15

Pick & Place System

- Robotics Arm
 - Suited for highly stacked warehouse
 - Agile in reaching difficult storage location
 - Cargo would be retrieved or stored at a fixed location



- Automatic Guided Vehicle
 - Suited for manoeuvring of racks of cargo
 - Flexible in pick & place cargo in different location
 - Easier in adapting expansion and reduction



Transportation Robot

- Automatic Guided Vehicle to follow predetermined path
- Carrying payload ranging from 50 -1200 kg
- Equipped with different path following technique
- Safety network to enhance safety with auto resume feature





Control Unit

Inventory Management

- Reading / Writing of the database according to inventory changes
- Retrieving inventory from rack according to order
- Statistic of change for inventory
- Coordination
 - Coordinate of components to achieve management option
 - Monitoring system status for safety and inventory management
 - Equipped with simple to use Graphical User Interface to access and control

Home	Manual	I/O Monitor	Log	Setting			12:53:27 2020四月/28 (星期二
System Status				Required End mill		Finished request	
Start Pau	se Debug Order D	ebug Dialog Emer	gency Stop	Storage ID	End Mill	Storage ID	Location
Time elapse	d Pro	ogress	End mill statistics	1224	K-OB52*3-0.2-1	577	AGV
			BR	1153	K-OB49.5*3-1	585	AGV
0m:10s	1	0/22		1154	K-OB50#3-1	600	AGV
				1155	K-OB52*3-1	602	AGV
				1156	K-OB78*3-1	611	AGV
System status: Auto mode running. System operation: Getting End Mill.			1	K-DD41.5*20-1	1516	AGV	
			2	K-OB10*2-2	871	AGV	
				3	K-OB10*2-4	1591	AGV
Motor Status				4	K-OB10*2.5-2	1595	AGV
				5	K-OB10*3-2	1223	AGV
				6	K-OB10*3.5-2		
				7	K-OB10*4-2		
Robot Arm System 1.	0			MD	М		Powered by Apound



Reference Projects : The Billie Upcycling (2018)





types Textiles simultaneously



of inventories between points



orders at the same time



Reference Projects : CNC Punching & 3D Projects (2020 - Current)





Control Unit SHO

Order list &



Advanced Robotics Solution



What is Advanced Robotics Solution?







Collaboration between Human & Robots A platform for installing maneuvering different terrain Customized tools/applicator designed for dedicated purpose



Advantages of Robotics Automation Solution

Γ	\forall	1
2		<u> </u>
	\sim	_

Allowing the robot to access hazardous area or hard to reach area



Perform repetitive/scheduled work with less margin of error/ better consistency



Promote better use of manpower on simple / labor intensive work



Components of Robotics System





Control Unit

Perform analyzing of signal received to output desired action



Safety Sensor

Network of sensors will be included to allow safe interaction between human and the robot

Remote Control

Wireless / Wired / Autonomous control can be achieved

Stationary/Moving platform to carry load and perform task under the command

Chassis



Chassis

Wheeled Chassis

- Relatively Agile in movement
- Best suited for flat and smooth terrain
- Allows for better longevity for travelling long distance



Tracked Chassis

- Better weight distribution for carry high load
- Best suited for wide variety of terrain, from smooth to rough
- Able to move in soft surface such as mud / shallow water



Patrol / Surveillance

▷ Equip with :



Surveillance Camera



▷ Enables :

- 24/7 Monitoring
- Autonomous Operation with less manpower
- Enable monitoring wide range of parameter
- Easy Monitoring of High-Risk Area

Customizable Solution

Mobile Pick & Place
 Heavy-Duty
 Delivering Robot

Indoor Mapping Robots









Recent Projects - Robotics-Enabled Automatic Fogger for Mosquito Control (2020 - Current)



Perform in AUTO mode

Adapts to fogger technology

```
Allows
chassis for different
      terrain
```



Robotics in Construction Industry



How Robots involve in Construction Industry?



Enables uniform quality with higher accuracy Replace human operators from tasks involve intensive physical work or work that exposed to dangerous environment Make task that are beyond human capabilities easier



GoGo Trolley

- Designed by In-House designer team
- Awarded CITF's Pre-Approved Product
- Improve workers health & safety
- Provide large customizability







Features of GoGo Trolley







Responsive Remote Control

Up to 300kg of loading

Extensive Customizability







Environmentally Friendly Power Source Tracked Chassis for Rough Terrain

Comprehensive Safety Network



QuicaBot

- Develop & Designed by Transforma Robotics with Singapore's Nanyang Technological University
- Designed as a solution for housing quality inspection & assessment
- With different advanced sensors, quantify different parameters of housing inspection





TRANSFORMA





Features of QuicaBot



Multi-Operating Mode – Autonomous / Following / Remote Control



Realtime Upload to Private / Public Cloud



Ease in Expanding Sensor Network for different function







Reduce Inspection time up to 50%

Up to **4hrs of Battery Life** with Interchangeable Battery

pollo

Promote efficiency in manpower, saving up to 50%

Technology of QuicaBot

QuicaBot is equipped with multiple advanced sensors for detecting different defects and performing different functions





PictoBot

- Develop & Designed by Transforma Robotics with Singapore's Nanyang Technological University
- Designed for easy maneuvering in indoor area, such as going though corridors & doors
- Developed with intelligent model for high efficiency and the best quality



TRANSFORMA





Features of PictoBot



High Spraying Efficiency





Up to 4 times faster than conventional painting method

Able to paint walls up to 3m tall







In-situ Optical Scanning & 3D Model Building



Quantitative Painting process model for planning process

Conclusion

Karmo Apollo + Robotics Automation + Government

嘉模阿波羅 + 智能機械自動化與 香港政府攜手走向





The End

